













- 28 [10,369,704](#)  [Base systems for supporting soft robotic actuators](#)
- 29 [10,349,927](#)  [Soft retractors](#)
- 30 [10,208,925](#)  [Soft conformal laparoscopic instrument](#)
- 31 [10,189,168](#)  [Soft robotic actuator enhancements](#)
- 32 [10,179,411](#)  [Soft robotic grippers for cluttered grasping environments, high acceleration movements, food manipulation, and automated storage and retrieval systems](#)
- 33 [10,179,410](#)  [Modular robotic systems](#)
- 34 [10,173,328](#)  [Soft robotic actuators and methods of manufacturing the same](#)
- 35 [10,172,602](#)  [Soft robotic retractors](#)
- 36 [10,118,301](#)  [Soft robotic actuator attachment hub and grasper assembly, reinforced actuators, and electroadhesive actuators](#)
- 37 [10,112,310](#)  [Food handling gripper](#)
- 38 [10,093,023](#)  [Enhancement of soft robotic grippers through integration of stiff structures](#)
- 39 [10,046,462](#)  [Self-contained robotic gripper system](#)
- 40 [10,028,734](#)  [Soft robotic retractors](#)
- 41 [9,975,251](#)  [Soft robotic actuators for positioning, packaging, and assembling](#)
- 42 [9,956,745](#)  [Rigidized inflatable structures](#)
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